

**Blow Applicator with Swing Cylinder  
Type 3100 / Type 3100H  
Part-No. 5535914 / 5537966**

**Operating Instructions**

Edition 10/03



## Blow Applicator with Swing Cylinder



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## 1. Product Description

### Function

The Blow Applicator with Swing Cylinder is an extra device to use with label printers for automatically applying the printed label onto the product.

The applicator is equipped with a swing cylinder. This makes it possible to apply the labels at vertical areas. In the case of use the applicator at a label printer Apollo it is also possible to apply upward.

The labels are transferred with a pad, which swings between the two positions, starting position and labelling position, by a compressed-air driven pneumatic cylinder.

In the starting position, the label is picked up from the printer.

The position of the pad in the starting position is signaled by a sensor. The label is removed from the carrier ribbon directly at the dispense edge of the printer. It is sucked on the pad by a vacuum via drillings at the bottom of the pad. For support, the label is also blown against the pad with an air current coming from a blow tube. The correct transfer from the label is controlled by a vacuum sensor.

Next, the pad is moved into the labelling position, which is confirmed by another sensor (labelling position sensor). Here, the label is blown onto the product by blow air from the pad.

While the pad is moving back into the starting position, the vacuum sensor controls whether the label has been removed from the pad.

Specially adapted pads can be used for different label sizes.

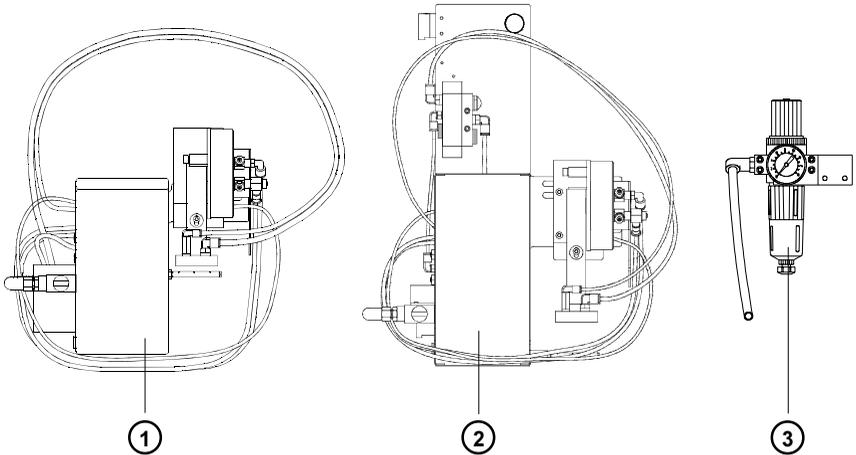
The control unit of the applicator is connected with the printer on its SPI interface using the peripheral connector of the printer.

For operation in a network system the applicator's PLC (programmable logic control) interface with potential free inputs and outputs can be used.

### Technical Data

	Apollo	Hermes
Label width :	12-112 mm	10-112 mm
Label height :	12-70 mm	10-80 mm
Air pressure :	5 bis 6 bar	5 bis 6 bar
Turning angle		
Swing Cylinder :	115° (forward) 205° (upward)	115° (forward)

## 2. Equipment Supplied



**Fig. 2 Equipment Supplied**

**1 - Blow Applicator with Swing Cylinder Type 3100  
for the Transfer Printer Apollo**

incl. 4 Cylinder-head Screws  
4 Washers  
4 Spring Washers

**incl. Blow Pad Unit (customized)**

- Pad  
- Blow Tube

**2 - Blow Applicator with Swing Cylinder Type 3100H  
for the Transfer Printer Hermes**

incl. 2 Hinges  
4 Screws  
1 Knurled Screw

**incl. Blow Pad Unit (customized)**

- Pad  
- Blow Tube

**3 - Service Unit (Option)**

incl. 2 Screws  
2 Washers

Other options on request !

### 3. Safety Instructions



**CAUTION !**

**Make sure that the printer is disconnected from the power supply and the valve at the service unit as well as the shutoff valve at the applicator are closed, while installing the delivered components !**



**CAUTION !**

**In operation, moving parts are easily accessible. Therefore, keep long hair, loose clothes, and jewellery distant.  
Before any manipulations in those areas, close the shutoff valve !**

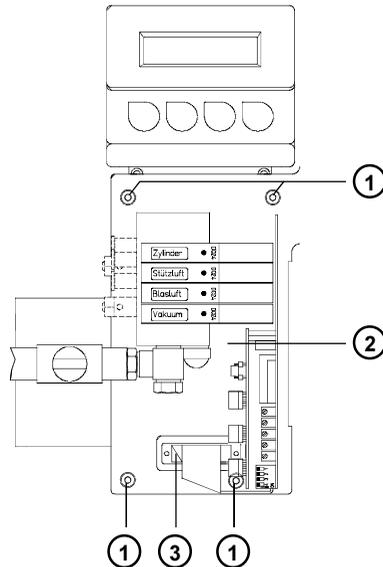


**CAUTION !**

**Do not try to manipulate or repair parts that are not described in the manuals of the blow applicator or the printer !**

## 4. Installation

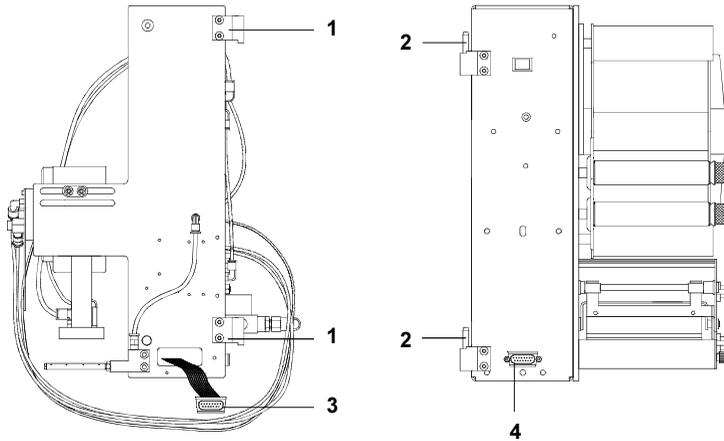
### Installing the Blow Applicator on the Apollo



**Fig. 4a Installation of the Blow Applicator on the Apollo**

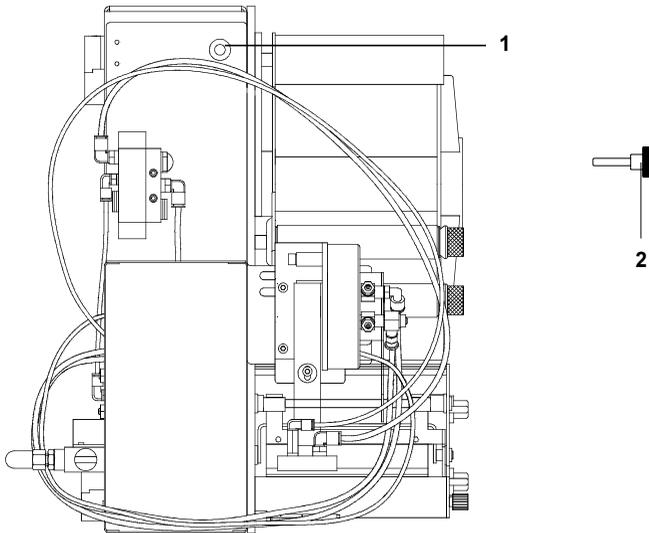
1. Dismantle the casing of the manifold (2) by loosening the screws, two on the left and one on the right.
2. Fasten the applicator at the front of the **Apollo** using the four supplied screws (1) including the washers.
3. Plug the connector (3) of the applicator's electronic system in the peripheral port of the **Apollo**.
4. Reassemble the casing of the manifold.

## Installing the Blow Applicator on the Hermes



**Fig. 4b Installation of the Blow Applicator on the Hermes**

1. Fasten the two hinges (2) included in the equipment on the Hermes using the supplied screws.
2. Hang the applicator with its two hinges (1) into the hinges (2) of the Hermes.
3. Turn the applicator towards the **Hermes** as far as necessary to plug the connector of the applicator-electronics into the peripheral connector for cab-applicators on the front of the printer.
4. Contact the connector (3) of the applicator-electronics to the peripheral connector (4) of the Hermes.



**Fig. 4c Fastening the Blow Applicator**

5. Attach the applicator on the Hermes by screwing the knurled screw (2) into the hole (1).

## Installing the Service Unit

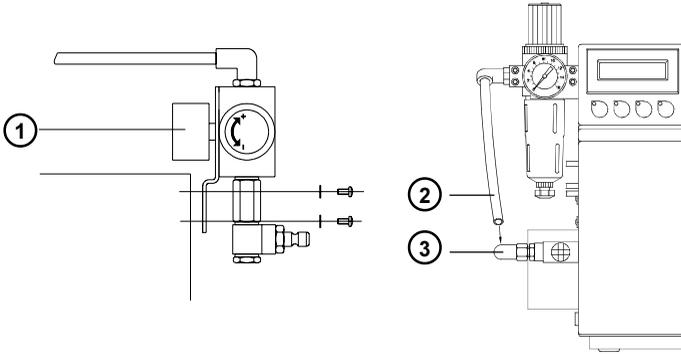


Fig. 4d Installation of the Service Unit on the Apollo

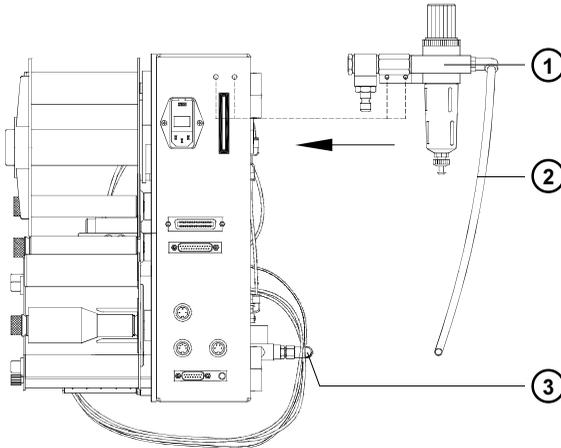
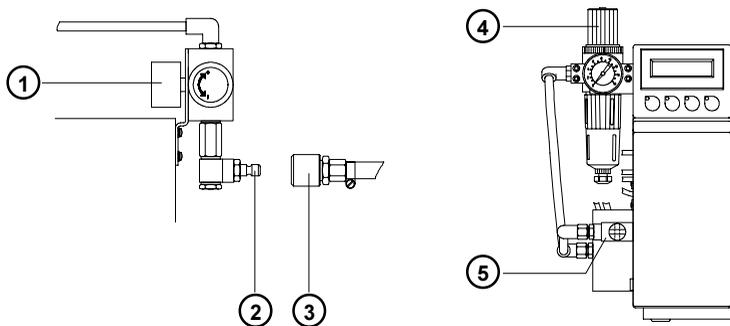


Fig. 4e Installation of the Service Unit on the Hermes

1. Fasten the service unit (1) at the back of the **Apollo** and/or the **Hermes** using the washers and the screws .
2. Insert the tube of the service unit (2) into the push-in-T-fitting (3) at the external blow valve.  
Insert tube firmly.

## Connections



**Fig. 4f Connections**

1. Prepare the connections to the power supply and to the computer as described in the manual of the printer.
2. To contact the PLC interface use the 15-pin connector at the manifold (for further details see appendix A).
3. Make sure that the shutoff valve (5) is closed (lever at the valve is turned vertical).
4. The connector (2) for the compressed air supply is located at the service unit (1) at the rear of the printer.  
The connector is suitable for a 1/4" coupling plug (3).
5. The air pressure for operating the applicator has to be adjusted at the service unit (1).
  - Pull knurled knob (4) up.
  - Turn knob to tune required operating pressure (5-6 bar).  
By turning knob clockwise the pressure rises.
  - Push knob down.
6. Switch on the power supply of the printer.
7. Open the shutoff valve. (5/ lever is turned horizontal)

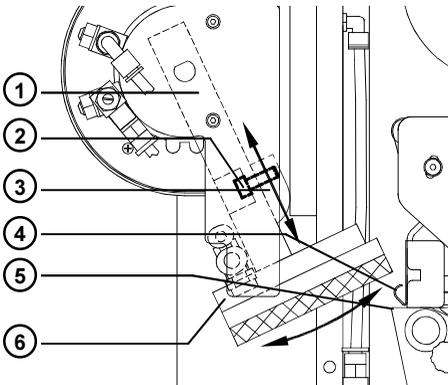
## 5. Adjustments

All supplied label applicators have passed a previous run at the factory.

It may be useful to do some more fine tuning when the applicator is installed. This refers mainly to those parameters, which are significant as part of a networked system as well as pneumatic settings, which have an influence on the application rate.

### 5.1. Mechanical Adjustments

#### Angle of the Pad in the Starting Position

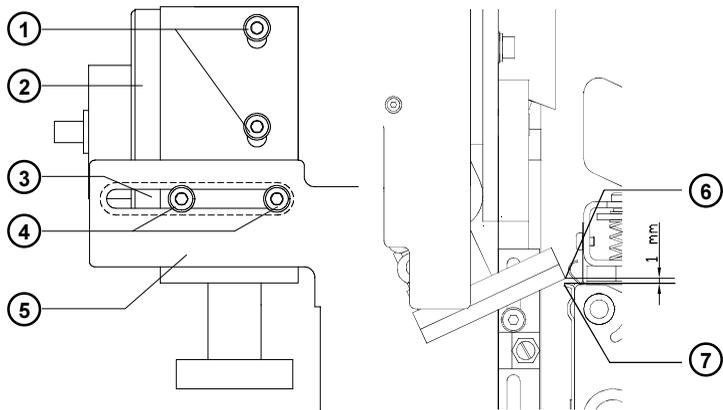


**Fig. 5.1a Adjusting the Angle of the Pad in the Starting Position**

In the position where the label is picked up (starting position), the pad (6) is swung towards the printer in a certain angle. This angle can be adjusted by sliding the stud (3).

The angle is optimized when, in the starting position, the rear edge of the pad (6) is located vertically above the dispense edge (5) without touching the ribbon shield (4).

1. Loosen the screw (2).
2. Move the stud (3) along the pad holder (1).  
By sliding the stud (3) up the pad swings close by the ribbon shield.
3. Tighten the screw (2).

**Adjusting the Level and the Sides of the Cylinder Unit on the Apollo****Fig. 5.1b Level Adjustment / Side Adjustment on the Apollo****Side Adjustment**

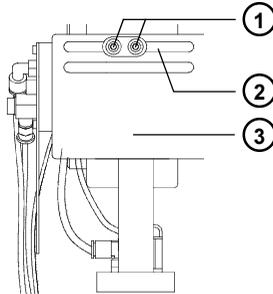
1. Loosen both bottom screws (4) on the rear side of the mounting plate (5) of the blow applicator type 3100.
2. Move the cylinder unit (2) within the longish hole (3) until the dispensed label is aligned centrally to the pad.
3. Tighten the screws (4).

**Level Adjustment**

1. Loosen both upper screws (1) on the rear side of the mounting plate (5) of the blow applicator type 3100.
2. Move the cylinder unit until in its upper (starting) position the pad (6) is located slightly above the dispense edge (7) of the Apollo.  
The distance between the pad and the dispense edge is recommended to be around 1 mm.
3. Tighten screws (1).

### Adjusting the Level and the Sides of the Cylinder Unit on the Hermes

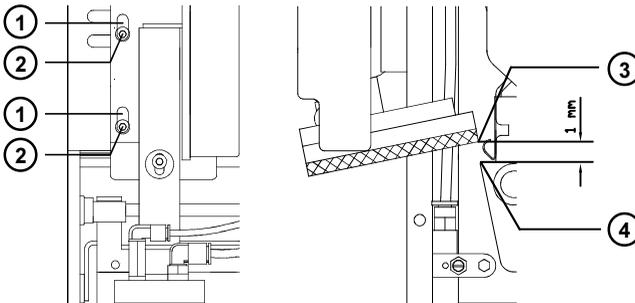
#### Side Adjustment



**Fig. 5.1c Side Adjustment on the Hermes**

1. Loosen both screws (1) on the rear side of the mounting plate (3) of the blow applicator type 3100H.
2. Move the cylinder unit within the longish hole (3) until the dispensed label is aligned centrally to the pad.
3. Tighten the screws (1).

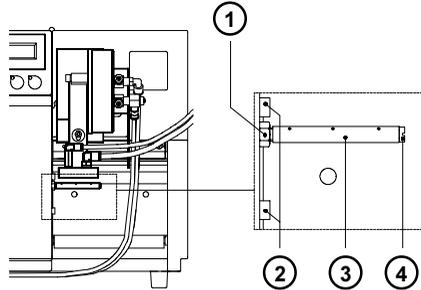
#### Level Adjustment



**Fig. 5.1d Level Adjustment on the Hermes**

1. Loosen both screws (2) on the front side of the blow applicator type 3100H.
2. Move the cylinder unit within the longish holes (1) until in its upper (starting) position the pad (3) is located slightly above the dispense edge (4). The distance between the pad and the dispense edge is recommended to be around 1 mm.
3. Tighten the screws (2).

### Tuning the Blow Tube



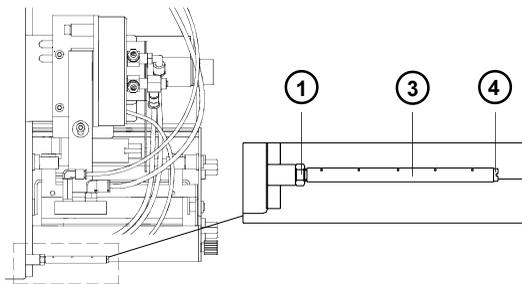
**Fig. 5.1e Tuning the Blow Tube on the Apollo**

#### Vertical adjustment

- Loosen the screws (2).
- Shift the blow tube (3) as required.
- Tighten screws (2).

#### Turn around longitudinal axis (Change the direction of the air current)

- Hold the slotted screw (4) with a screwdriver and loosen the counter nut (1).
- Adjust the tube (3) until the air current is aligned with the dispense edge of the printer.
- Tighten counter nut.



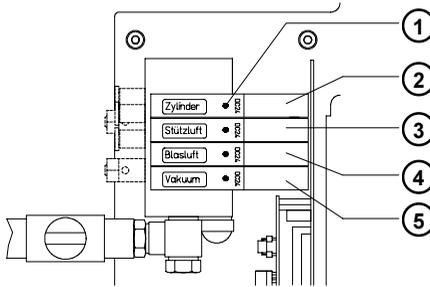
**Fig. 5.1f Tuning the Blow Tube on the Hermes**

#### Turn around longitudinal axis (Change the direction of the air current)

- Hold the slotted screw (4) with a screwdriver and loosen the counter nut (1).
- Adjust the tube (3) until the air current is aligned with the dispense edge of the printer.
- Tighten counter nut.

## 5.2. Pneumatic Adjustments

### Control Valves



**Fig. 5.2a Control Valves**

To reach the control valves, the casing of the manifold has to be removed. Therefore, loosen the screws at the cover, two on the left and one on the right.

That way, four electric switchable control valves for compressed air become accessible. For manual tuning, the valves can also be operated by integrated keys (1).

The functions of the valves are as explained below.

'Zylinder' (2/ swing cylinder) :

Two-way valve to control the swing cylinder.

When the valve is switched off the pad is kept in the starting position. Switching the valve on will move the pad to the labelling position. Normally the disconnection of the valve is controlled by the signal of the labelling position sensor. When operated manually, there is no controlling by the labelling position sensor. The pad moves to the bottom as far as possible and stays in that position until the key is released.

'Stützluft' (3/ supporting air) :

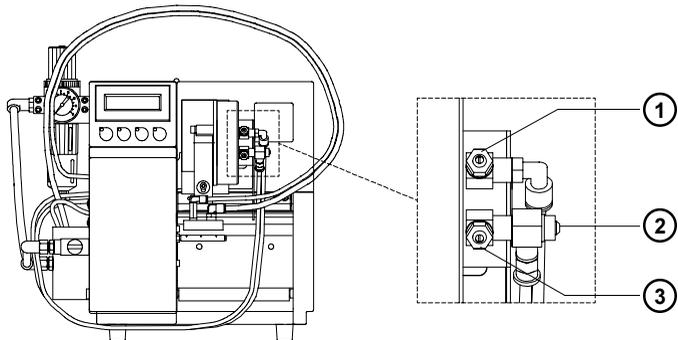
This valve controls the switch-on of the supporting air at the blow tube.

'Blasluft' (4/ blow air) :

This valve controls the external blow valve and thereby the switching on of the blow air at the pad.

'Vakuum' (5/ vacuum nozzle) :

This valve operates the vacuum nozzle and, consequently, controls the vacuum on the pad for picking up the label.

**Throttle Valves at the Cylinder****Fig. 5.2b Throttle Valves at the Cylinder**

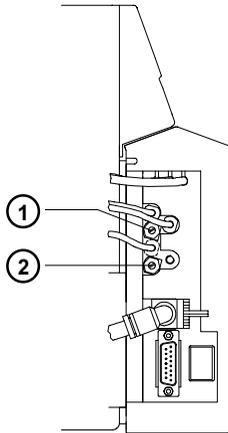
The setting of the cylinder can be regulated via two throttle valves (1, 3). Those valves regulate the speed with which the compressed air escapes the two air containers.

The valves are adjustable by turning the throttle screws. Turning clockwise will close the valves.

A wider opening of the bottom valve (3) speeds up the pad moving from the starting position to the labelling position, a wider opening of the top valve (1) accelerates the return movement.

A third throttle valve (2) limits the speed of the compressed air streaming into the bottom air container. By switching the machine on this valve damps the first movement of the pad into the starting position. At this time the top air container is empty, therefore, the setting of the top throttle valve (1) is ineffective to damp this movement.

### Throttle Valve at the Manifold



**Fig. 5.2c Throttle Valves at the Manifold**

Throttle valve to regulate the supporting air **(1)**

With this valve the supporting air to blow the label onto the pad can be adjusted.

Turn the throttle screw to adjust the valve. Turning clockwise will close the valve.

The valve has to be tuned in such a way, that the label is blown onto the pad without turning or swinging.

Throttle valve to regulate the vacuum **(2)**

With this valve the vacuum to suck the label onto the pad can be adjusted.

Turn the throttle screw to adjust the valve. Turning clockwise will close the valve.

The vacuum can be adjusted until the label totally sticks on the vacuum plate.

### 5.3. Selection of the Operation Mode

The blow applicator can be operated in three different ways referring to the order of printing and labelling of one applying cycle. A mode can be selected through actuating a DIP switch. All operating modes can be adjusted by setting different time delays.

Furthermore, there is a special mode using the pre-dispense key for adjusting, etc.

#### Operation Mode 'Printing / Labelling'

The print of a label is released by an external start signal (via PLC interface). At the same moment the vacuum on the pad as well as the supporting air from the blow tube are switched on. When the label is printed and picked up from the carrier ribbon, the supporting air is switched off and the swing cylinder is driven in such a way that the pad is swung into the labelling position. A sensor signals when the labelling position is reached.

Following, the vacuum is switched off, the blow air is switched on for a short time through which the label is placed onto the product. After that the swing cylinder is driven to move the pad back into the starting position. Thus, the labelling cycle is finished.

#### Operation Mode 'Labelling / Printing - Waiting in the Starting Position'

Before starting the mode 'labelling / printing' the printing and picking up of the first label has to be released separately by a special signal (via PLC interface).

The pad with the printed label is in the starting position. The vacuum on the plate is switched on.

By an external start signal, the swing cylinder is driven to swing the pad into the labelling position. The sensor signals when the labelling position is reached.

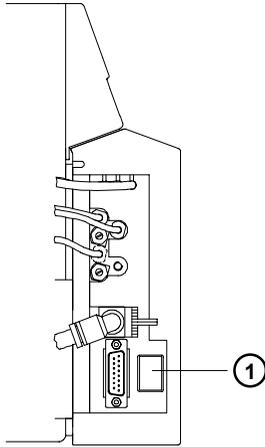
In the following the vacuum is switched off, the blow air is switched on for a short time through which the label is placed onto the product.

After that the swing cylinder is driven to move the pad back into the starting position. Now the next label is printed. At the same moment, the vacuum on the pad as well as the supporting air from the blow tube are switched on. When the label is printed and picked up from the carrier ribbon, the supporting air is switched off. Thus, the labelling cycle is finished.

#### Operation Mode 'Labelling / Printing - Waiting in the Labelling Position'

This mode differs from the above described mode 'Labelling / Printing - Waiting in the Starting Position' in so far as the printed label is immediately moved into the labelling position and is being held there. Consequently the next cycle begins by blowing the label onto the product.

### Function of the Pre-dispense Key



**Fig. 5.3a Pre-dispense Key**

By pressing the pre-dispense key (1), half cycles of the labelling process can alternately be released, provided that there is a print job.

#### **1(st) half cycle**

Pressing the key will release the print of one label. At the same moment the vacuum at the pad as well as the supporting air (blow tube) are switched on. After the label has been printed and picked up by the pad, the supporting air is switched off.

#### **2(nd) half cycle**

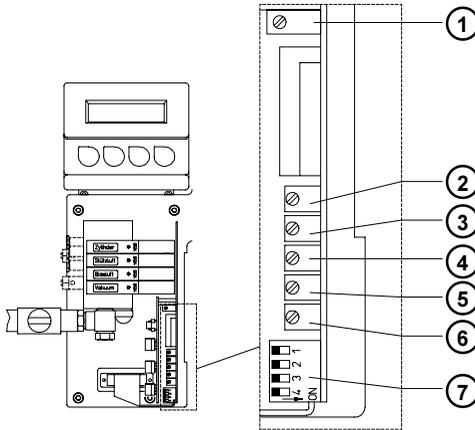
Pressing the key will drive the swing cylinder to move the pad down into the labelling position. The sensor signals when the labelling position is reached. Following, the vacuum is switched off and the label is placed onto the product by blowing. Then, the swing cylinder is driven to move the pad back into the starting position.

If the label is removed from the pad manually after the first half cycle of the labelling process, the print process will be repeated when the pre-dispense key is pressed again.

If there is no print job, only the movements of the pad as described for the second part of the labelling cycle are carried out, pressing the key.

The first half cycle of the labelling process can also be released by pressing the  key on the control panel of the printer. In that case, a blank label is picked up by the pad. That way, the whole labelling process can be simulated by alternately pressing the  key and the pre-dispense key without the need of a print job or a connection to a computer.

### Setting the Operation Mode and Delay Times



**Fig 5.3b Potentiometers and DIP-Switches**

For best adaptation, the applicator offers several methods to adjust to the whole system and, therefore, to the required needs.

After removing the cover of the manifold, 6 potentiometers as well as 4 DIP switches become accessible by which the parameters can be set.

#### Potentiometers

Potentiometer 1 is sealed. Certain voltage settings are pre-adjusted from the factory and not to be changed by the user.

The potentiometers 2 - 6 offer the adjustment of the labelling process by changing certain time delays. If any one of the settings is changed the actual value is briefly shown in the printer display.

Potentiometer (2) :  $t_B$  - blowing time 0 ... 2.5 s

This potentiometer is used to set the time period of the blow air for the transfer of the label onto the product.

Potentiometer (3) :  $t_{SA}$  - switch-off delay supporting air 0 ... 2.5 s

Delayed to the process of the label being picked up, the supporting air is switched off.

In many cases, after being picked up by the pad the label edge may still stick on the carrier ribbon. This may affect the accuracy of the label positioning or even cause faults in the labelling.

Therefore, switching off the air blow delayed can be useful to separate the label from the carrier ribbon and neatly place the label on the surface of the pad.

Potentiometer (4) :  $s_{SE}$  - switch-on delay supporting air 0 ... 20 mm

The supporting air from the blow tube is not immediately switched on when the print of the label is released but delayed. The air is switched on, when the label has covered a certain distance  $s_{SE}$ .

This delay helps to prevent a turning or swinging at the front of the label and, consequently, avoids faults when the label is being picked up from the printer.

The parameter measures the distance covered by the label before the supporting air is switched on, and it is not dependent on the print speed. This way, the position of the label can be determined until the air is switched on.

Potentiometer (5) :  $t_{SP}$  - locking time 0 ... 2.5 s

All start signals coming in following the first start signal are ignored when they arrive within the locking time  $t_{SP}$ .

Potentiometer (6) :  $t_{VS}$  - start delay 0 ... 2.5 s

The parameter  $t_{VS}$  determines the time period between the start signal and the start of the labelling process. With this delay it is possible to release the start of the labelling process sensor controlled, for instance, when a sensor is located on an assembly line in front of the labelling place.

### DIP Switches

With the DIP switches (7) the operation mode as well as the firmware of the applicator can be determined.

DIP-Switch	Parameter	ON	OFF
1	Waiting position in the operation mode Labelling/Printing (only DIP2 OFF and DIP3 OFF)	Starting Position	Labelling Position
2	Applicator	Tamp applicator	Blow applicator
3	Operation mode	Printing / Labelling	Labelling / Printing
4	Save potentiometer settings	no	yes

If switch No. 4 is OFF the setting of the potentiometers is automatically stored in the printer when switched on. Therefore, in case the applicator has been changed (e.g. in case of an accident) the settings are still saved and can be transferred to a replacement (see also Print info display).

## Print Info Display

**Apollo and Hermes** offer a convenient option for recalling information about the configuration and hardware problems in the printer info display (see also Operator's Manual of the printer).

First, press the  key to switch from ONLINE mode into OFFLINE

mode. Next, to recall the printer information desired, press the  key to see the first of the five display pages available. Press key repeatedly to view the other pages. When an applicator is installed, this display is extended by another five pages. After the standard pages, the following parameters are shown :

- start delay
- locking time
- switch-off delay supporting air
- blowing time
- switch-on delay supporting air.

When the reviewing is completed, switch back into ONLINE mode by pressing the  key.

In case the applicator has been changed (e.g. in case of an accident) the stored parameters can be viewed as described above and the new device can be adjusted accordingly. For that purpose the DIP-switch 4 at the new applicator has to be 'ON' during switching on the device the first time.

## 6. Operation



1. **Check all external connections before starting to print.**
2. Make sure that the media is loaded corresponding to the instructions of the Operator's Manual of the appropriate printer  
 Apollo : chapter 'Options'  
 'Present Sensor/Inserting the Labels for Peel-off'  
 Hermes : chapter 'Media Loading'  
 'Loading Labels'
3. Check that the transfer ribbon is loaded properly before starting to print (see Operator's Manual of the printer).
4. Make sure that the pad is not covered by a label when switching on the device.
5. Open the shutoff valve.
6. Switch into the present mode of the printer during programming and set the peel position to remove the labels from the carrier ribbon corresponding to the size of the label.



7. **Before starting the first print job press the  key on the printer.**

This generates a synchronous running. Remove the processed labels manually. After a few seconds the printer carries out a brief rewind and the edge of the next label is positioned at the print line.

This synchronizing also has to be carried out when the print job

has been interrupted with the  key.

8. Start the print job.
9. Start the labelling process via PLC interface.

If an error occurs while the applicator is operating, this is shown in the display of the printer (for types of errors and how to treat them see appendix B)

## Blow Applicator with Swing Cylinder

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## Appendix A - PLC Interface

For use in a networked system the applicator is equipped with a PLC interface to start and interrupt the labelling process. It also passes on state information as well as error messages of the applicator to the system control.

The interface has a 15 pin SUB-D connector.

### Pin Assignment of the PLC Interface

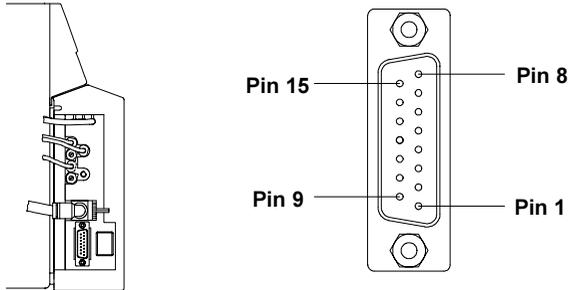


Fig. A-1 Connector of the PLC Interface

PIN	Signal	Direction	Function
1	XSTRT	input	start signal
2	XSTP	input	stop signal
3	XDREE	input	print first label
4	XDNB	output	printer not ready
5	XEDG	output	no existing print job
6	XSAA	output	general error message
7	XSOE	output	pad in starting position
8	GND	output	grounding (0V)
9	XSTRTR	(input)	start signal (reverse line)
10	XSTPR	(input)	stop signal (reverse line)
11	XDREER	(input)	print first label (reverse line)
12	XSUE	output	pad in labelling position
13	XETF	output	applicator fault
14	RÜL	output	reverse line (for all output signals)
15	24P	output	operating voltage +24V, Si T 100mA

Table A-1 Pin Assignment of the PLC Interface

### Circuit Diagrams of Inputs and Outputs

The **inputs** are optocouplers with a current limiting resistor of  $2.4k\Omega$  in the input circuit.

For each signal X[IN] there is a separate reverse line X[IN]R via the plug connector. From that, the following matching pairs of signals result :

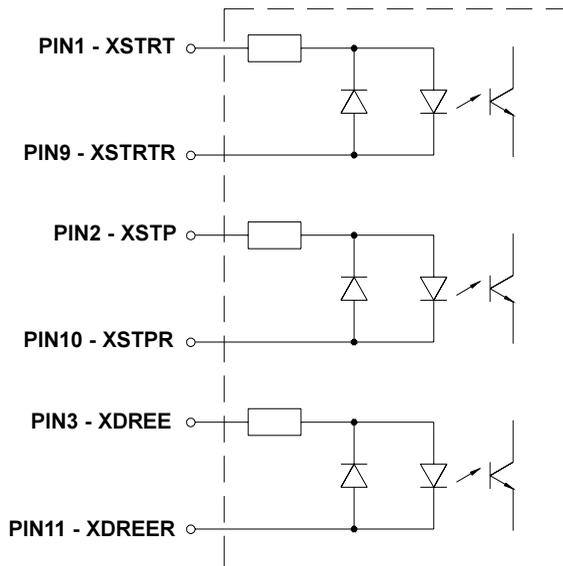


Fig. A-2 Circuit of the Inputs

All **outputs** are realized through solid state relays which outputs are connected among one another one-sided. The joint line is lead to the plug connector as RÜL signal.  
 The switch function of the outputs is to open or close the contact between the joint line RÜL and the respective output.

Electrical requirements :  $U_{\max} = 42V$   
 $I_{\max} = 100mA$

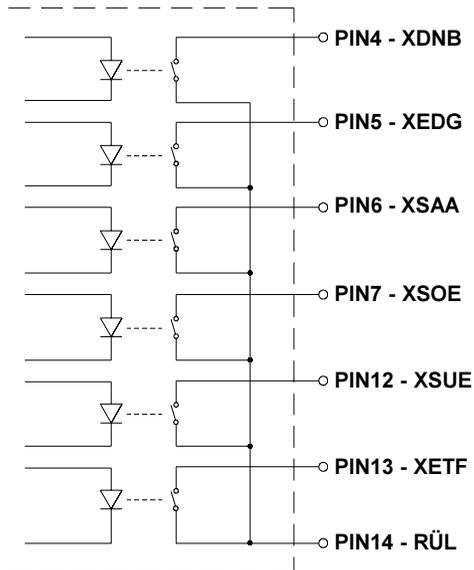


Fig. A-3 Circuit of the Outputs

### Comments on the Signals

#### **PIN1 - XSTRT** - Start signal

This signal will release the start of the labelling process. It is active when a current flows between PIN1 and PIN9.

#### **PIN2 - XSTP** - Stop signal

The signal is active when a current flows between PIN2 and PIN10. It releases following functions :

- to finish the print of a label and its picking-up by the pad
- to interrupt or to stop the beginning of the labelling process
- to make the pad moving back into the starting position
- to command the disregard of all following signals
- if the stop signal has been activated during the labelling phase, the display will show the message 'Host stop/ error'. (does not show message during print process)

#### **PIN3 - XDREE** - Print first label

When current flows between PIN3 and PIN11 the print of the first label and its picking-up by the pad is released within the operation mode 'Labelling / Printing'.

When the labelling process is started by the XSTRT signal within the operation mode 'Labelling / Printing', the cylinder will start to place the label onto the product at once. Only after that, a new label is printed.

Therefore, the provision of the first label has to be assigned by a separate signal.

In the 'Printing / Labelling' mode this signal has no function.

#### **PIN4 - XDNB** - Printer not ready

This is an error message of the printer.

The details and type of error can be learnt from the printer display. ('Ribbon out'; 'Paper out'; 'No label')

In this state the contact between PIN4 and PIN14 is opened.

After error correction, the print of the last label will be repeated.

**PIN5 - XEDG - No existing print job**

State message.

There is no print job currently available.

In this state the contact between PIN5 and PIN14 is opened.

**PIN6 - XSAA - General error message**

General error message of both, printer and applicator.

This message is shown when one of the two errors either XDNB or XETF occurs. This signal is important in case that only one error signal of the applicator can be analysed from the system control.

In this state the contact between PIN6 and PIN14 is opened.

**PIN7 - XSOE - Pad in starting position**

The signal is active when the pad is in the starting position where it picks up the label from the printer.

In this state the contact between PIN7 and PIN14 is opened.

**PIN8 - GND - Grounding (0V)**

**PIN9 - XSTRTR - Reverse line of the start signal XSTRT**

**PIN10 - XSTPR - Reverse line of the stop signal XSTP**

**PIN11 - XDREER - Reverse line of the print first label signal XDREE**

**PIN12 - XSUE - Pad in labelling position**

The signal is active when the pad is in its labelling position where the label is removed from the vacuum plate and positioned onto the product.

In this state the contact between PIN12 and PIN14 is opened.

**PIN13 - XETF - Applicator fault**

This is an error message of the applicator.

This message is shown when one of the following errors occurs at the applicator :

- pad has not reached the labelling position within 2s after the movement of the cylinder
- pad has not reached the starting position within 2s after the movement of the cylinder
- a printed label has not been picked up by the pad properly or it fell down during the movement of the cylinder (message of the vacuum sensor)
- the label is still on the vacuum plate of the pad when the cylinder moves back up (message of the vacuum sensor)

The type of fault is shown in the display of the printer.

In this state the contact between PIN13 and PIN14 is opened.

After fault correction, the print of the last label printed before the fault occurred will not be repeated.

**PIN14 - RÜL - Reverse line (for all output signals)**

**PIN15 - 24P - Operating voltage +24V, Si T 100mA**

There is an operating voltage of 24V available on PIN15 provided from the applicator system.



**CAUTION !**

**You must not apply any external voltage on PIN15 !**

The operating voltage on the plug connector allows the use of the applicator without being part of a networked system. The start signal which is required for releasing the labelling process may be caused, for instance, by a suitable foot controlled switch with a 15 pin SUB-D plug.

Examples for Circuits to Creating a Start Signal

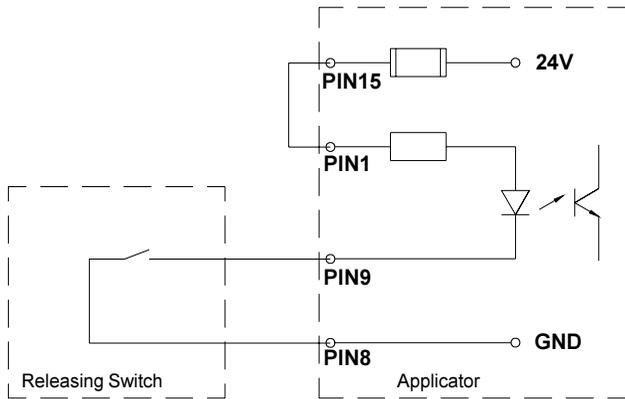
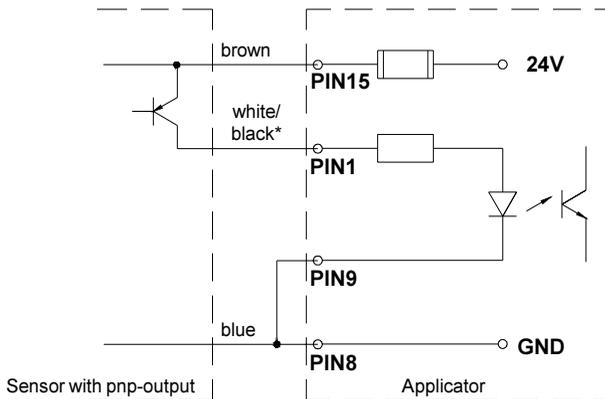


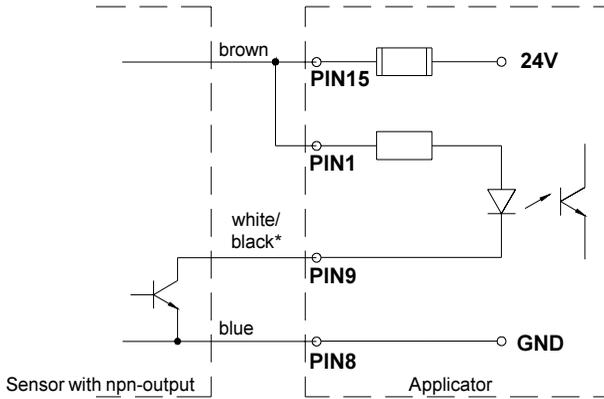
Fig. A-4 Example with releasing switch



\* dependent on the used sensor

Fig. A-5 Example for an optical sensor with pnp-output

## Applicator - PLC Interface



\* dependent on the used sensor

**Fig. A-6 Example for an optical sensor with npn-output**

## Appendix B - Error Messages

### Error Messages of the Printer

Detailed information about printer errors (e.g. 'Paper out', 'Ribbon out', etc.), their causes and correction methods can be found in the Operator's manual of the printer (Appendix C).



With the installation of an applicator the error treatment expands. This means in particular, that after correcting the error and **before** the

correction is quit with the  key, an additional label feed has to be

released using the  key. This synchronizes the process of printing and labelling. Possibly dispensed blank labels have to be removed manually.

After quitting the error message the label caused the error will be printed once more.

### Error Messages of the Applicator

The following table gives an overview of error messages and their possible cause. It also suggests methods to resolve the problem. After error correction, always quit the error message of the applicator

with the  key.

To reprint the label where the applicator error occurred, a new print job has to be released.

## Applicator - Error Messages

<b>Error message</b>	<b>Possible cause</b>	<b>Solution</b>
Label not depos.	Label has not been placed onto the product; after the lift has moved back the label still sticks on the vacuum plate of the pad	Label the product manually
Upper position	Pad has not reached the starting position within 2s after the lift has moved back; or Pad has left the starting position unauthorized	Check the pneumatic adjustments (esp. the upper throttle valve of the cylinder); Label the product manually
Host stop /error	Labelling process has been interrupted by an XSTP stop signal via PLC interface	Label the product manually if necessary
Refl. sensor blk.	There has been no change of the switch state at the upper control sensor (at the cylinder) between the start of the labelling process and the signal from the labelling position sensor	Check the sensor (service)
Vac. plate empty	Label has not been picked up properly by the pad; or Label fell off the pad before it could be placed onto the product	If possible, place the 'lost' label onto the product manually; Otherwise stop print job and start again with adapted parameters (e.g. count)
Lower position	Pad has not reached the labelling position within 2s after the movement of the cylinder	Check the pneumatic adjustments (esp. the lower throttle valve of the cylinder); Check the applicator for heaviness of its mechanics; Label the product manually

**Table B-1 Error Messages of the Applicator**

## Appendix C - Function of the LEDs of the Electronics

### PLC Port PCB

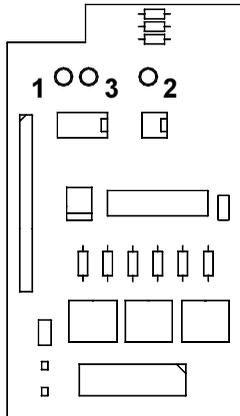
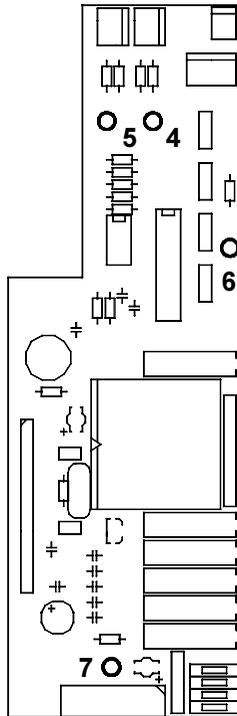


Fig. C-1 LED on the PLC port PCB

LED No.	Colour	Function	Active state
1	green	PLC signal XSTRT	ON
2	green	PLC signal XSTP	ON
3	green	PLC signal XDREE	ON

Table C-1 LED on the PLC Port PCB

**PCB Applicator Control**



**Fig. C-2 LED on the Applicator Control PCB**

LED-Nr.	Colour	Function	Active state
4	red	Sensor signals that pad is in labelling position	OFF
5	red	Sensor signals that pad is in starting position	ON
6	yellow	Label on the pad	ON
7	yellow	Operating voltage 5V	ON

**Table C-2 LED on the applicator control PCB**

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## EC-Conformity Declaration

Herewith we declare that the following described machine, from the design and style and as we sell it, complies with the relevant EC Safety and Health Requirements.

This declaration will lose the validity if there are any changes of the machine or the purpose without our consent.

Description:  
**Applicator**

Type:  
**Blow Applicator  
with Swing Cylinder**

Applied EC Regulations and Norms:

- |  |   |
|--|---|
| - <b>EC-Machinery Directive</b>                                  | <b>98/37/EU</b>   |
| - Machine Safety   | EN 292-2:1991 + A1:1995   |
| - <b>EC Low Voltage Regulations</b>                              | <b>73/23/EEC</b>  |
| - Data and Office Machine Safety                                 | EN60950:1992 + A1:1993<br>EN 60950/A2:1993 +<br>A3:1995 + A4:1997 |
| - <b>EC Electromagnetic Compatibility Regulations</b>            | <b>89/336/EEC</b>   |
| - Threshold values for the Interference<br>of Data Machines      | EN 55022:1998   |
| - Limits for harmonic current emission                           | EN 61000-3-2:1995 +<br>A1:1998 + A2:1998 + A14:2000               |
| - Limits of voltage fluctuation and flicker                      | EN 61000-3-3:1995   |
| - Immunity characteristics-<br>Limits and methods of measurement | EN 55024:1998   |

Signature for the producer:

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Sömmerda, 15.07.03

Erwin Fascher  
Managing Director